## Generative Adversarial Networks (GANs) & Restricted Boltzmann Machines (RBMs)

Lecture 24

Changho Suh

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### Outline

1. Investigate a training method for RBM.

2. Introduce a loss function, and discuss its theoretical background.

3. Study how to compute the loss function.

### How to train RBM $\theta := (W, b, c)$



## Given visible units with *m* examples:

$$\{v^{(i)}\}_{i=1}^{m}$$

#### **Iterative** algorithm:

- $v^{(t),(i)}$  : estimate of visible units w.r.t. *i*-th example at the *t*-th iteration
- $h^{(t),(i)}$  : estimate of hidden units

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Training procedure 
$$\theta := (W, b, c)$$



Given visible units with mexamples:

$$\{v^{(i)}\}_{i=1}^{m}$$

Step 1: Sample  $h^{(t),(i)} \sim \mathbb{P}(h|v^{(t),(i)}) \quad \forall i \in \{1, \dots, m\}$  $\mathbb{P}(h|v^{(t),(i)}) = \frac{e^{c^{(t)T}h + h^T W^{(t)}v^{(t),(i)}}}{\sum_h e^{c^{(t)T}h + h^T W^{(t)}v^{(t),(i)}}}$ 

Step 2: Sample  $v^{(t),(i)} \sim \mathbb{P}(v|h^{(t),(i)}) \quad \forall i \in \{1, \dots, m\}$  $\mathbb{P}(v|h^{(t),(i)}) = \frac{e^{b^{(t)T}v + v^T W^{(t)T}h^{(t),(i)}}}{\sum_v e^{b^{(t)T}v + v^T W^{(t)T}h^{(t),(i)}}}$ 

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Training procedure 
$$\theta := (W, b, c)$$



# Given visible units with *m* examples:

$$\{v^{(i)}\}_{i=1}^{m}$$

**Step 1:** Sample  $h^{(t),(i)} \sim \mathbb{P}(h|v^{(t),(i)}) \quad \forall i \in \{1, \dots, m\}$ **Step 2:** Sample  $v^{(t),(i)} \sim \mathbb{P}(v|h^{(t),(i)}) \quad \forall i \in \{1, \dots, m\}$ 

**Step 3:** Compute a cost function:

$$J^{(t)}(\theta) := \frac{1}{m} \sum_{i=1}^{m} \ell\left(v^{(i)}, v^{(t),(i)}\right)$$

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Training procedure 
$$\theta := (W, b, c)$$



## Given visible units with *m* examples:

$$\{v^{(i)}\}_{i=1}^{m}$$

**Step 1:** Sample  $h^{(t),(i)} \sim \mathbb{P}(h|v^{(t),(i)}) \quad \forall i \in \{1, \dots, m\}$  **Step 2:** Sample  $v^{(t),(i)} \sim \mathbb{P}(v|h^{(t),(i)}) \quad \forall i \in \{1, \dots, m\}$  **Step 3:** Compute a cost function:  $J^{(t)}(\theta)$  **Step 4:** Update parameters via gradient descent:  $\theta^{(t+1)} \leftarrow \theta^{(t)} - \alpha^{(t)} \nabla J^{(t)}(\theta)$ 

Loss function  $\ell(v^{(i)}, v^{(t),(i)})$ ?

## **Turns out:** The following loss is optimal in a certain sense:

$$\ell_{\text{opt}}(v, \hat{v}) = F(v) - F(\hat{v})$$
  
free energy  
where  $F(v) = -\log\left(\sum_{h} e^{-E(v,h)}\right)$ 

### How to compute the loss function?

$$\ell_{\text{opt}}(v, \hat{v}) = F(v) - F(\hat{v})$$
  
where  $F(v) = -\log\left(\sum_{h} e^{-E(v,h)}\right)$ 

**Recall:** 
$$E(v,h) := -b^T v - c^T h - h^T W v$$
  
 $F(v) = -\log\left(\sum_h e^{b^T v + c^T h + h^T W v}\right) = -\log\left(e^{b^T v} \sum_h e^{c^T h + h^T W v}\right)$   
 $= -b^T v - \log\left(\sum_h e^{c^T h + h^T W v}\right)$ 

### So far ...

### Have learned about DNNs, CNNs, RNNs, RFs, dimensionality reduction, clustering, autoencoder, matrix completion, GANs, and RBMs.

### **RFs**: Small-data technique!

There are more advanced small-data techniques, part of which rely upon autoencoder and matrix completion:

semi-supervised learning transfer learning simulator-based learning

### Look ahead

Will explore three small-data techniques:

- 1. semi-supervised learning
- 2. transfer learning
- 3. simulator-based learning