### **Dimensionality reduction & clustering**

Lecture 16

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### **Recap: DTs**

A decision-based model of the tree structure.

Training algorithm: **CART** 

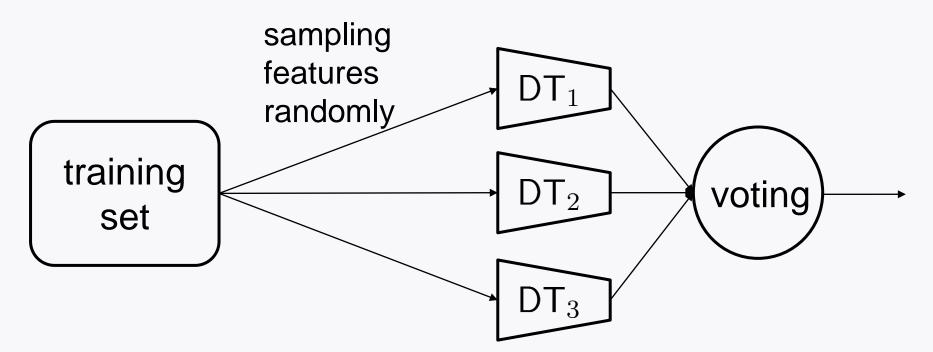
#### Hyperparameters:

"max\_depth" "min\_samples\_split"
"max\_leaf\_nodes" "min\_samples\_leaf"

Challenge: Sensitive to small variations in training data

### Recap: RFs

An ensemble of DTs, each trained on the random subspace method



Hyperparameters: "max\_features" "n\_estimators" A measure for *interpretation*: Feature importance

# **Recap: Coding for DTs and RFs**

from sklearn.tree import DecisionTreeClassifier

from sklearn.tree import plot\_tree

```
tree_clf = DecisionTreeClassifier(max_depth=2)
tree_clf.fit(X_train,y_train)
plot tree(tree clf)
```

from sklearn.ensemble import RandomForestClassifier
rnd\_clf = RandomForestClassifier(n\_estimators=500,max\_leaf\_nodes=16)
rnd\_clf.fit(X\_train,y\_train)
feature\_importances = rnd\_clf.feature\_importances\_

# **Recap: Coding for hyperparameter search**

from sklearn.model\_selection import GridSearchCV
forest\_clf=RandomForestClassifier(max\_depth=2)
param\_grid={'n\_estimators':[3,10,100,500],'max\_features':[1,2,3,4]}
grid\_search=GridSearchCV(forest\_clf,param\_grid,cv=5,scoring='accuracy')
grid\_search.fit(X\_train,y\_train)

randomized\_search.fit(X\_train,y\_train)

randomized\_search.best\_params\_
randomized\_search.best\_estimator\_
randomized\_search.best\_estimator\_.feature\_importances\_

### Question

So far: Learned about DNNs, CNNs, RNNs & RFs.

What if still unsatisfactory performances?

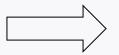
This may be due to:

- 1.  $n \gg m \leftarrow \# \text{ of examples}$  and/or `data dimension
- 2. data distribution is pretty wide.

i.e., data characteristics are quite distinct across examples.

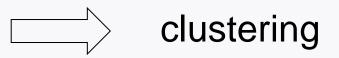
### **Techiques for addressing such scenarios**

#### Scenario 1: $n \gg m$



dimensionality reduction

#### **Scenario 2:** data distribution is pretty wide.



## **Outline of today's lecture**

Will study dimensionality reduction & clustering:

- Explore the most popular dimensiona reduction technique: Principal Component Analysis (PCA)
- Investigate another prominent technique:
   t-distributed Stochastic Neighbor Embedding (t-SNE)
- 3. Study clustering methods.

### **Focus of Lecture 16**

Will study dimensionality reduction & clustering:

- 1. Explore the most popular dimensiona reduction technique: Principal Component Analysis (**PCA**)
- Investigate another prominent technique:
   t-distributed Stochastic Neighbor Embedding (t-SNE)
- 3. Study clustering methods.

# **Dimensionality reduction**

Reducing # of features in data by obtaining a set of principal components

#### Three major roles:

- 1. Improve generalization performance
- 2. Speed up training
- 3. Data visualization

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# Principal Component Analysis (PCA)

#### The most popular dimensionality reduction technique!



Karl Pearson 1901

# **PCA** in words

A technique that does the following:

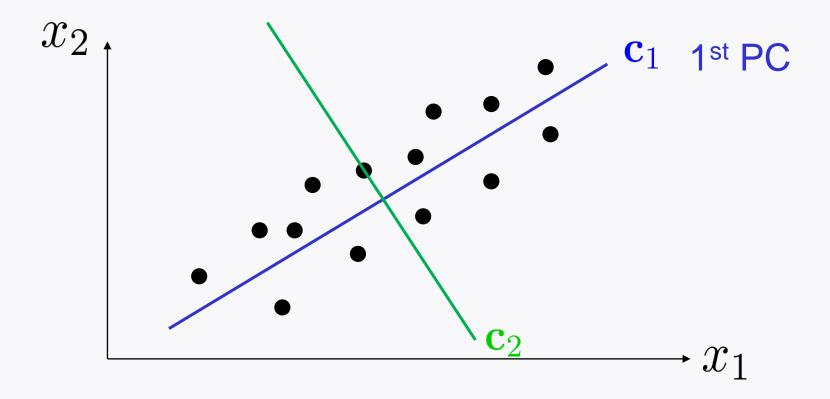
1. Identify a <u>vector</u> along which data points are most explained. 1<sup>st</sup> principal component (PC)

2<sup>nd</sup> PC

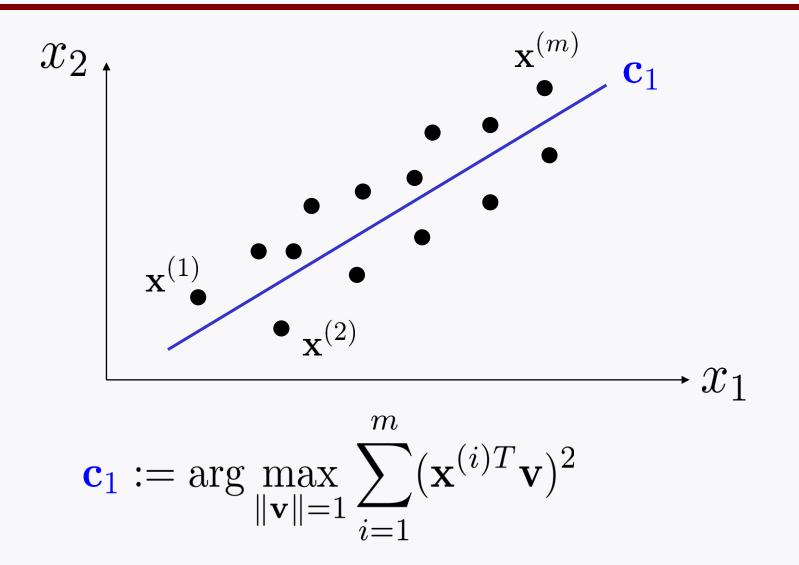
2. Find another vector along which data points are most explained subject to orthogonality to the 1<sup>st</sup> one

3. Repeat until reaching desired # of vectors.

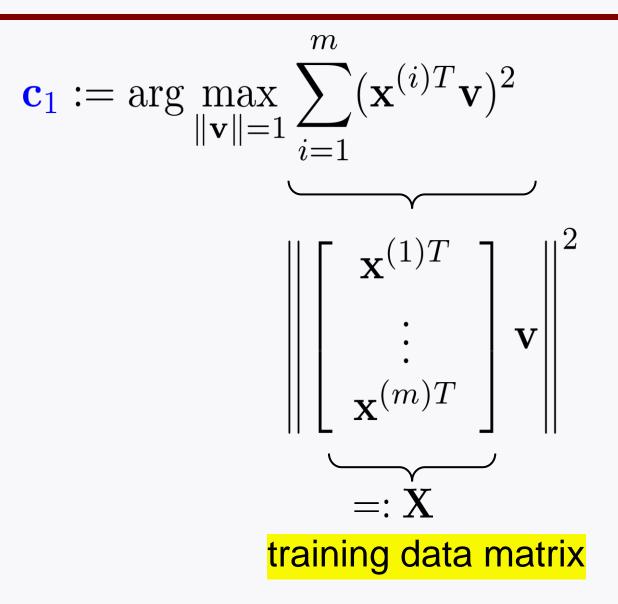
# **PCA** in picture



Find a vector along which data points are most *spread*. Similarly find another vector yet orthogonal to 1<sup>st</sup> one.



$$\mathbf{c}_{1} := \arg \max_{\|\mathbf{v}\|=1} \underbrace{\sum_{i=1}^{m} (\mathbf{x}^{(i)T} \mathbf{v})^{2}}_{\substack{i=1}{}} \\ \left\| \begin{bmatrix} \mathbf{x}^{(1)T} \mathbf{v} \\ \vdots \\ \mathbf{x}^{(m)T} \mathbf{v} \end{bmatrix} \right\|^{2}$$



$$\mathbf{c}_{1} := \arg \max_{\|\mathbf{v}\|=1} \underbrace{\sum_{i=1}^{m} (\mathbf{x}^{(i)T} \mathbf{v})^{2}}_{\mathbf{v}^{T} \mathbf{X}^{T} \mathbf{X} \mathbf{v}}$$
symmetric matrix  
Eigenvalue decomposition:  $\mathbf{X}^{T} \mathbf{X} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^{T}$   
 $\mathbf{\Lambda} = \operatorname{diag}(\lambda_{1}, \dots, \lambda_{n})$   
 $\mathbf{V} = [\mathbf{v}_{1}, \dots, \mathbf{v}_{n}]$ 

m $\mathbf{c}_1 := \arg \max_{\|\mathbf{v}\|=1} \sum_{i=1}^{\infty} (\mathbf{x}^{(i)T} \mathbf{v})^2$  $\mathbf{v}^T \mathbf{X}^T \mathbf{X} \mathbf{v}$  $\mathbf{X}^T \mathbf{X} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^T$ n $=\sum \lambda_i (\mathbf{v}^T \mathbf{v}_i)^2$  $\mathbf{\Lambda} = \mathsf{diag}(\lambda_1, \ldots, \lambda_n)$  $\mathbf{V} = |\mathbf{v}_1, \dots, \mathbf{v}_n|$ i=1 $\lambda_1 > \cdots > \lambda_n$  $ightarrow \mathbf{v}^* = \mathbf{v}_1$ 

$$\mathbf{c}_{1} := \arg \max_{\|\mathbf{v}\|=1} \sum_{i=1}^{m} (\mathbf{x}^{(i)T} \mathbf{v})^{2} \quad \rightarrow \mathbf{c}_{1} = \mathbf{v}_{1}$$
$$\mathbf{X}^{T} \mathbf{X} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^{T} \quad \mathbf{V} = [\mathbf{v}_{1}, \dots, \mathbf{v}_{n}]$$

 $\mathbf{c}_1 = \mathbf{v}_1$  (1<sup>st</sup> eigenvector of  $\mathbf{X}^T \mathbf{X}$ )

 $(1^{st}$  singular vector of  $\mathbf{X})$ 

### How to find PCs?

$$\begin{split} \mathbf{X} &:= \begin{bmatrix} \mathbf{x}^{(1)T} \\ \vdots \\ \mathbf{x}^{(m)T} \end{bmatrix} \in \mathbf{R}^{m \times n} & \text{training data matrix} \\ \mathbf{V} &= \begin{bmatrix} \mathbf{v}_1 \ \mathbf{v}_2 \ \cdots \mathbf{v}_n \end{bmatrix} \\ \mathbf{X}^T \mathbf{X} &= \mathbf{V} \mathbf{\Lambda} \mathbf{V}^T \end{split}$$

"d" number of PCs

$$\mathbf{c}_1 = \mathbf{v}_1$$
  
 $\mathbf{c}_2 = \mathbf{v}_2$   
 $\mathbf{c}_d = \mathbf{v}_d$ 

### How to choose d?

Choose *d* so as to explain a sufficiently large portion of data (e.g., 95%)

A measure that captures the proportion of data reflected in a principal component:

EVR (explained variance ratio)  $\in [0,1]$ 

Choose *d* such that:

$$\sum_{i=1}^{d} \mathsf{EVR}(\mathbf{c}_i) \approx 0.95$$

# PCA output?

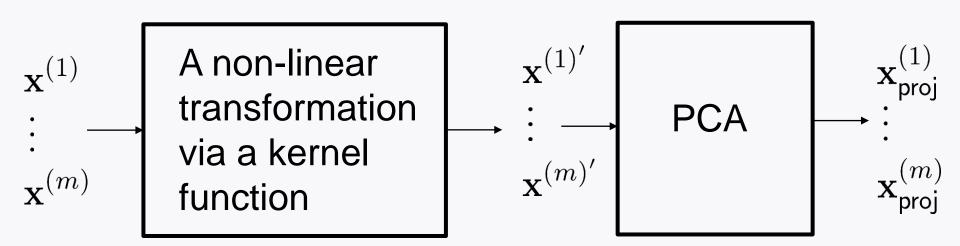
$$\begin{split} \mathbf{X} &:= \begin{bmatrix} \mathbf{x}^{(1)T} \\ \vdots \\ \mathbf{x}^{(m)T} \end{bmatrix} \in \mathbf{R}^{m \times n} \text{ training data matrix} \\ \mathbf{V}_d &= \begin{bmatrix} \mathbf{v}_1 \ \mathbf{v}_2 \ \cdots \mathbf{v}_d \end{bmatrix} \text{ principal components matrix} \\ \mathbf{x}_{\mathsf{proj}}^{(1)T} &= \begin{bmatrix} \mathbf{x}^{(1)T} \mathbf{v}_1, \dots, \mathbf{x}^{(1)T} \mathbf{v}_d \end{bmatrix} = \mathbf{x}^{(1)T} \mathbf{V}_d \\ \mathbf{X}_{\mathsf{proj}} &= \begin{bmatrix} \mathbf{x}_{\mathsf{proj}}^{(1)T} \\ \vdots \\ \mathbf{x}_{\mathsf{proj}}^{(m)T} \end{bmatrix} = \mathbf{X} \mathbf{V}_d \end{split}$$

# **Another technique?**

**Note:** PCA is a linear technique.

There is a non-linear version of PCA:

#### **Kernel PCA**



#### Look ahead

#### Will study another non-linear technique:

#### t-distributed Stochastic Neighbor Embedding (t-SNE)